

2018-10-24-1

Last Time: $W_m = \int_0^\lambda i d\lambda^*$ $f^c = -\frac{\partial W_m}{\partial x}$ $i = \frac{\partial W_m}{\partial \lambda}$

Today: use i, x as independent variables

$$\frac{dW_m}{dt} = i \frac{d\lambda}{dt} - f^c \frac{dx}{dt}$$

$$\frac{d(i\lambda)}{dt} = i \frac{d\lambda}{dt} + \lambda \frac{di}{dt} \quad \Rightarrow \quad i \frac{d\lambda}{dt} = \frac{d(i\lambda)}{dt} - \lambda \frac{di}{dt}$$

$$\frac{dW_m}{dt} = \frac{d(i\lambda)}{dt} - \lambda \frac{di}{dt} - f^c \frac{dx}{dt} \quad \Rightarrow \quad \frac{d(W_m - i\lambda)}{dt} = -\lambda \frac{di}{dt} - f^c \frac{dx}{dt}$$

$$\frac{d(i\lambda - W_m)}{dt} = \lambda \frac{di}{dt} + f^c \frac{dx}{dt}$$

define co-energy: $W_m' = i\lambda - W_m$

$$\frac{dW_m'}{dt} = \lambda \frac{di}{dt} + f^c \frac{dx}{dt}$$

i and x are independent variables!

$$\frac{dW_m'}{dt} = \frac{\partial W_m'}{\partial i} \frac{di}{dt} + \frac{\partial W_m'}{\partial x} \frac{dx}{dt}$$

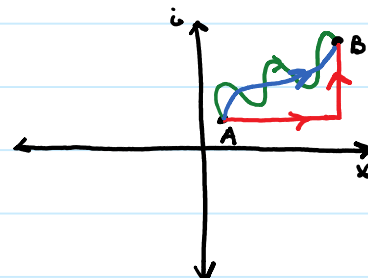
$$\lambda = \frac{\partial W_m'}{\partial i} \quad f^c = \frac{\partial W_m'}{\partial x}$$

* So, like before once the co-energy is known, f^c can be found by differentiating.

$$\frac{dW_m'}{dt} = \lambda \frac{d\dot{u}}{dt} + f^c \frac{dx}{dt} \Rightarrow dW_m' = \lambda d\dot{u} + f^c dx$$

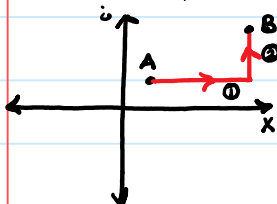
$$\int_{W_{m0}'}^{W_m'} dW_m' = \int_{\dot{u}_0}^{\dot{u}} \lambda d\dot{u} + \int_{x_0}^x f^c dx$$

$$W_m' - W_{m0}' = \int_{\dot{u}_0}^{\dot{u}} \lambda d\dot{u} + \int_{x_0}^x f^c dx$$



* Again, conservative field: path independence

* Select path for most easy integration.



* set $\dot{u}_0 = 0$ and say $f^c(\dot{u}=0) = 0$

* on ①: $\dot{u} = 0 = \text{constant}$

$$\int \lambda d\dot{u} = 0$$

$$\int_{x_0}^x f^c dx = 0$$

* on ②

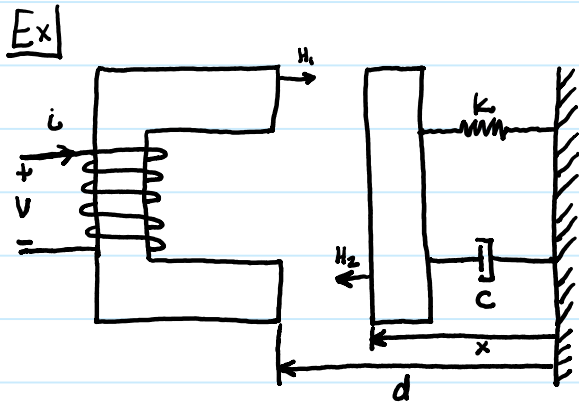
$$\int \lambda d\dot{u} \neq 0$$

$$\int f^c dx = 0$$

$$\Rightarrow W_m' = \int_0^{\dot{u}} \lambda d\dot{u} \quad f^c = \frac{\partial W_m'}{\partial x}$$

if $\lambda = L(\dot{u}) \Rightarrow W_m' = \int_0^{\dot{u}} L(\dot{u}) d\dot{u} \Rightarrow W_m' = \frac{1}{2} L(\dot{u}) \dot{u}^2$

$$f^c = \frac{\partial W_m'}{\partial x} \Rightarrow f^c = \frac{1}{2} \frac{\partial L}{\partial x} \dot{u}^2$$



$$\Phi = \left[\frac{\mu_0 AN}{2(d-x)} \right] i$$

$$\lambda = N\Phi \Rightarrow \lambda = \left[\frac{\mu_0 AN^2}{2(d-x)} \right] i$$

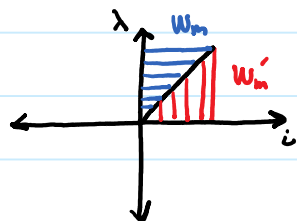
$$W_m' = \int_0^i \left[\frac{\mu_0 AN^2}{2(d-x)} \right] i^* di^* \Rightarrow W_m' = \frac{1}{2} \left[\frac{\mu_0 AN^2}{2(d-x)} \right] i^2$$

$$f^e = \frac{\partial W_m'}{\partial x} \Rightarrow f^e = \frac{1}{2} \left[\frac{\mu_0 AN^2}{2(d-x)^2} \right] i^2 = \frac{1}{2} \left[\frac{2}{\mu_0 N^2 A} \right] \lambda^2$$

* Same as when using \$W_m\$, as expected!

Energy vs. Coenergy

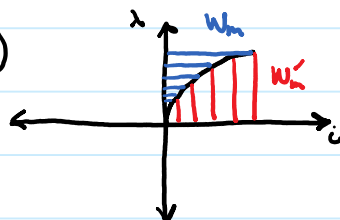
$$W_m = \int_0^\lambda i d\lambda^* \quad W_m' = \int_0^i \lambda di^*$$



$$W_m + W_m' = \lambda i \quad \text{as expected}$$

$$\text{if } \lambda = L(i) i \quad (\text{linear}) \Rightarrow W_m = W_m'$$

\$\lambda = f(i, x)\$ (non-linear)



$$W_m + W_m' = \lambda i \quad \text{as expected}$$

$$W_m \neq W_m'$$

Multiple input system: For example, rotor-stator system

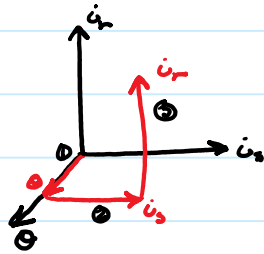
$$\lambda_s = L_s \dot{i}_s + L_m(\theta) \dot{i}_r$$

$$\lambda_r = L_m(\theta) \dot{i}_s + L_r \dot{i}_r$$

$$\frac{dW_m'}{dt} = \lambda_s \frac{d\dot{i}_s}{dt} + \lambda_r \frac{d\dot{i}_r}{dt} + T^e \frac{d\theta}{dt}$$

$$\Rightarrow W_m' = \int_{\dot{i}_{s0}}^{\dot{i}_s} \lambda_s d\hat{i}_s + \int_{\dot{i}_{r0}}^{\dot{i}_r} \lambda_r d\hat{i}_r + \int_{\theta_0}^{\theta} T^e d\hat{\theta}$$

Path:



$$\dot{i}_{r0} = \dot{i}_{s0} = 0$$

$$T^e(\dot{i}_r=0, \dot{i}_s=0) = 0$$

$$\text{a) } \odot: \int_0^{\dot{i}_s} \lambda_s d\hat{i}_s = \int_0^{\dot{i}_r} \lambda_r d\hat{i}_r = 0 \quad \int_0^{\theta} 0 d\hat{\theta} = 0$$

$$\text{a) } \ominus: \int_0^{\dot{i}_s} \lambda_s(\hat{i}_s, 0, \theta) d\hat{i}_s \neq 0 \quad \int_0^{\dot{i}_r} \lambda_r d\hat{i}_r = \int_0^{\theta} T^e d\hat{\theta} = 0$$

$$\text{a) } \ominus: \int_0^{\dot{i}_r} \lambda_r(\dot{i}_s, \hat{i}_r, \theta) d\hat{i}_r \neq 0 \quad \int_0^{\dot{i}_s} \lambda_s d\hat{i}_s = \int_0^{\theta} T^e d\hat{\theta} = 0$$

$$W_m' = \int_0^{\dot{i}_s} \lambda_s(\hat{i}_s, 0, \theta) d\hat{i}_s + \int_0^{\dot{i}_r} \lambda_r(\dot{i}_s, \hat{i}_r, \theta) d\hat{i}_r$$

$$T^e = \frac{\partial W_m'}{\partial \theta}$$

$$\Rightarrow \boxed{W_m' = \frac{1}{2} L_s \dot{i}_s^2 + L_m(\theta) \dot{i}_r \dot{i}_s + \frac{1}{2} L_r \dot{i}_r^2}$$

$$T^e = \frac{\partial L_m}{\partial \theta} \dot{i}_r \dot{i}_s$$